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### 10-BIT DIGITAL-TO-ANALOG CONVERTERS

#### **FEATURES**

- 10-Bit CMOS Voltage Output DAC in an 8-Terminal Package
- 5V Single Supply Operation
- 3-Wire Serial Interface
- High-Impedance Reference Inputs
- Voltage Output Range: 2 Times the Reference Input Voltage
- Internal Power-On Reset
- Low Power Consumption: 1.75mW Max
- Update Rate of 1.21MHz
- Settling Time to 0.5LSB: 12.5μs Typ
- Monotonic Over Temperature
- Pin-Compatible With the Maxim MAX515

#### **APPLICATIONS**

- Battery-Powered Test Instruments
- Digital Offset and Gain Adjustment
- Battery Operated/Remote Industrial Controls
- Machine and Motion Control Devices
- Cellular Telephones

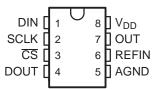
#### DESCRIPTION

The TLC5615 is a 10-bit voltage output digital-to-analog converter (DAC) with a buffered reference input (high impedance). The DAC has an output voltage range that is two times the reference voltage, and the DAC is monotonic. The device is simple to use, running from a single supply of 5V. A power-on-reset function is incorporated to ensure repeatable start-up conditions.

Digital control of the TLC5615 is over a three-wire serial bus that is CMOS compatible and easily interfaced to industry standard microprocessor and microcontroller devices. The device receives a 16-bit data word to produce the analog output. The digital inputs feature Schmitt triggers for high noise immunity. Digital communication protocols include the SPI<sup>TM</sup>, QSPI<sup>TM</sup>, and Microwire<sup>TM</sup> standards.

The 8-terminal small-outline D package allows digital control of analog functions in space-critical applications. The TLC5615C is characterized for operation from 0°C to +70°C. The TLC5615I is characterized for operation from -40°C to +85°C.

## D, P, OR DGK PACKAGE (TOP VIEW)





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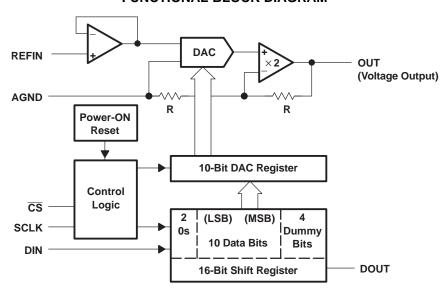




This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### **FUNCTIONAL BLOCK DIAGRAM**



#### **Terminal Functions**

TERMINAL		I/O	DESCRIPTION				
NAME	NO.	1/0	DESCRIPTION				
DIN	1	I Serial data input					
SCLK	2	I Serial clock input					
CS	3	I Chip select, active low					
DOUT	4	0	Serial data output for daisy chaining				
AGND	5		Analog ground				
REFIN	6	1	Reference input				
OUT	7	0	DAC analog voltage output				
$V_{DD}$	8		Positive power supply				

#### PACKAGE/ORDERING INFORMATION

For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.



#### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted)(1)

		UNIT		
Supply voltage (V <sub>DD</sub> to AGND)		7V		
Digital input voltage range to AGND		-0.3V to V <sub>DD</sub> + 0.3V		
Reference input voltage range to AGND		-0.3V to V <sub>DD</sub> + 0.3V		
Output voltage at OUT from external source		V <sub>DD</sub> + 0.3V		
Continuous current at any terminal		±20mA		
Operating free-air temperature range, T <sub>A</sub>	TLC5615C	0°C to +70°C		
	TLC5615I	-40°C to +85°C		
Storage temperature range, T <sub>stg</sub>		−65°C to +150°C		
Lead temperature 1,6mm (1/16 inch) from case for 10 seconds		+260°C		

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### RECOMMENDED OPERATING CONDITIONS

			MIN	NOM	MAX	UNIT
Supply voltage, V <sub>DD</sub>			4.5	5	5.5	V
High-level digital input voltage, V <sub>IH</sub>						V
Low-level digital input voltage, V <sub>IL</sub>					0.8	V
Reference voltage, V <sub>ref</sub> to REFIN terminal			2	2.048	V <sub>DD</sub> –2	V
Load resistance, R <sub>L</sub>			2			kΩ
Operation from air temperature T	TLC5615C		0		70	°C
Operating free-air temperature, T <sub>A</sub>	TLC5615I		40		85	°C

#### **ELECTRICAL CHARACTERISTICS**

over recommended operating free-air temperature range,  $V_{DD} = 5V \pm 5\%$ ,  $V_{ref} = 2.048V$  (unless otherwise noted)

STATIO	C DAC SPECIFICATIONS							
	PARAMETER		TEST CON	DITIONS	MIN	TYP	MAX	UNIT
	Resolution				10			bits
	Integral nonlinearity, end point a	djusted (INL)	$V_{ref} = 2.048V,$	See (1)			±1	LSB
	Differential nonlinearity (DNL)		$V_{ref} = 2.048V,$	See (2)		±0.1	±0.5	LSB
E <sub>ZS</sub>	Zero-scale error (offset error at zero scale)		$V_{ref} = 2.048V,$	See (3)			±3	LSB
	Zero-scale-error temperature co	efficient	$V_{ref} = 2.048V,$	See (4)		3		ppm/°C
$E_G$	Gain error		$V_{ref} = 2.048V,$	See (5)			±3	LSB
	Gain-error temperature coefficient	nt	$V_{ref} = 2.048V,$	See (6)		1		ppm/°C
PSRR	Dower cumply rejection ratio	Zero scale	See (7)(8)		80			dB
FORK	Power-supply rejection ratio	Gain	See (1/(3)		80			uБ
	Analog full scale output		$R_L = 100k\Omega$		2\	/ <sub>ref</sub> (1023/1024)		V

<sup>(1)</sup> The relative accuracy or integral nonlinearity (INL), sometimes referred to as linearity error, is the maximum deviation of the output from the line between zero and full scale excluding the effects of zero code and full-scale errors (see text). Tested from code 3 to code 1024.

(3) Zero-scale error is the deviation from zero-voltage output when the digital input code is zero (see text).

(4) Zero-scale-error temperature coefficient is given by:  $E_{ZS}$  TC =  $[E_{ZS}$  ( $T_{max}$ ) –  $E_{ZS}$  ( $T_{min}$ )] $V_{ref} \times 10^6/(T_{max} - T_{min})$ .

The differential nonlinearity (DNL), sometimes referred to as differential error, is the difference between the measured and ideal 1LSB amplitude change of any two adjacent codes. Monotonic means the output voltage changes in the same direction (or remains constant) as a change in the digital input code. Tested from code 3 to code 1024.

 <sup>(5)</sup> Gain error is the deviation from the ideal output (V<sub>ref</sub> – 1LSB) with an output load of 10kΩ excluding the effects of the zero-scale error.
(6) Gain temperature coefficient is given by: E<sub>G</sub> TC = [E<sub>G</sub>(T<sub>max</sub>) – E<sub>G</sub> (T<sub>min</sub>)]/V<sub>ref</sub> × 10<sup>6</sup>/(T<sub>max</sub> – T<sub>min</sub>).
(7) Zero-scale-error rejection ratio (EZS-RR) is measured by varying the V<sub>DD</sub> from 4.5V to 5.5V dc and measuring the proportion of this signal imposed on the zero-code output voltage.

Gain-error rejection ratio (EG-RR) is measured by varying the V<sub>DD</sub> from 4.5V to 5.5V dc and measuring the proportion of this signal imposed on the full-scale output voltage after subtracting the zero-scale change.



## **VOLTAGE OUTPUT (OUT)**

	PARAMETER	TEST CONDIT	TIONS	MIN	TYP	MAX	UNIT
Vo	Voltage output range	$R_L = 10k\Omega$		0		V <sub>DD</sub> -0.4	V
	Output load regulation accuracy	$V_{O(OUT)} = 2V$ ,	$R_L = 2k\Omega$			0.5	LSB
I <sub>osc</sub>	Output short circuit current	OUT to V <sub>DD</sub> or AGND			20		mA
$V_{OL(low)}$	Output voltage, low-level	I <sub>O(OUT)</sub> ≤ 5mA				0.25	V
$V_{OH(high)}$	Output voltage, high-level	I <sub>O(OUT)</sub> ≤– 5mA		4.75			V
REFERE	NCE INPUT (REFIN)						
VI	Input voltage			0		V <sub>DD</sub> -2	V
r <sub>i</sub>	Input resistance			10			ΜΩ
C <sub>i</sub>	Input capacitance				5		pF
DIGITAL	INPUTS (DIN, SCLK, CS)						
V <sub>IH</sub>	High-level digital input voltage			2.4			V
V <sub>IL</sub>	Low-level digital input voltage					0.8	V
I <sub>IH</sub>	High-level digital input current	$V_I = V_{DD}$				±1	μΑ
$I_{\rm IL}$	Low-level digital input current	V <sub>I</sub> = 0				±1	μΑ
C <sub>i</sub>	Input capacitance			8		pF	
DIGITAL	OUTPUT (DOUT)						
V <sub>OH</sub>	Output voltage, high-level	$I_O = -2mA$		V <sub>DD</sub> -1			V
V <sub>OL</sub>	Output voltage, low-level	I <sub>O</sub> = 2mA				0.4	V
POWER :	SUPPLY						
$V_{DD}$	Supply voltage			4.5	5	5.5	V
	Dower gunnly gurrent	V <sub>DD</sub> = 5.5V, No load, All inputs = 0V or V <sub>DD</sub>	V <sub>ref</sub> = 0		150	250	μΑ
I <sub>DD</sub>	Power supply current	V <sub>DD</sub> = 5.5V, No load, All inputs = 0V or V <sub>DD</sub>	V <sub>ref</sub> = 2.048V		230	350	μΑ
ANALOG	OUTPUT DYNAMIC PERFORMANCE						-
	Signal-to-noise + distortion, S/(N+D)	V <sub>ref</sub> = 1V <sub>PP</sub> at 1kHz + 2.048 code = 11 1111 1111 (1)	BVdc,	60			dB

<sup>(1)</sup> The limiting frequency value at  $1V_{PP}$  is determined by the output-amplifier slew rate.

## **DIGITAL INPUT TIMING REQUIREMENTS (See Figure 1)**

	PARAMETER	MIN	NOM	MAX	UNIT
t <sub>su(DS)</sub>	Setup time, DIN before SCLK high	45			ns
t <sub>h(DH)</sub>	Hold time, DIN valid after SCLK high	0			ns
t <sub>su(CSS)</sub>	Setup time, CS low to SCLK high	1			ns
t <sub>su(CS1)</sub>	Setup time, CS high to SCLK high	50			ns
t <sub>h(CSH0)</sub>	Hold time, SCLK low to CS low	1			ns
t <sub>h(CSH1)</sub>	Hold time, SCLK low to CS high	0			ns
t <sub>w(CS)</sub>	Pulse duration, minimum chip select pulse width high	20			ns
t <sub>w(CL)</sub>	Pulse duration, SCLK low	25			ns
t <sub>w(CH)</sub>	Pulse duration, SCLK high	25			ns

#### **OUTPUT SWITCHING CHARACTERISTICS**

PARAMETER		TEST CONDITIONS	MIN	NOM	MAX	UNIT
t <sub>pd(DOUT)</sub>	Propagation delay time, DOUT	$C_L = 50pF$			50	ns



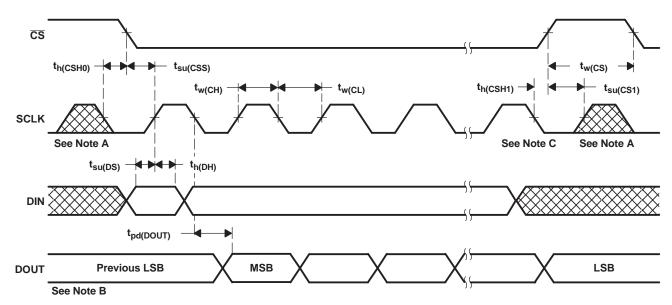
#### **OPERATING CHARACTERISTICS**

over recommended operating free-air temperature range,  $V_{DD}$  = 5V  $\pm$ 5%,  $V_{ref}$  = 2.048V (unless otherwise noted)

PARAMETER			MIN	TYP	MAX	UNIT	
ANAL	OG OUTPUT DYNAMIC PE	RFORMANCE		"		'	
SR	Output slew rate	$C_L = 100pF,$ $T_A = +25^{\circ}C$	$R_L = 10k\Omega$ ,	0.3	0.5		V/μs
t <sub>s</sub>	Output settling time	To 0.5LSB, $R_L = 10k\Omega$ ,	C <sub>L</sub> = 100pF, <sup>(1)</sup>		12.5		μs
	Glitch energy	DIN = All 0s to al	l 1s		5		nV-s
REFE	RENCE INPUT (REFIN)					,	-
	Reference feedthrough	REFIN = 1V <sub>PP</sub> at	REFIN = 1V <sub>PP</sub> at 1kHz + 2.048Vdc (2)		-80		dB
	Reference input bandwidth (f–3dB)	REFIN = 0.2V <sub>PP</sub>	REFIN = 0.2V <sub>PP</sub> + 2.048Vdc				kHz

<sup>(1)</sup> Settling time is the time for the output signal to remain within ±0.5LSB of the final measured value for a digital input code change of 000 hex to 3FF hex or 3FF hex to 000 hex.

#### PARAMETER MEASUREMENT INFORMATION



- NOTES: A. The input clock, applied at the SCLK terminal, should be inhibited low when  $\overline{\text{CS}}$  is high to minimize clock feedthrough.
  - B. Data input from preceeding conversion cycle.
  - C. Sixteenth SCLK falling edge

Figure 1. Timing Diagram

<sup>(2)</sup> Reference feedthrough is measured at the DAC output with an input code = 000 hex and a  $V_{ref}$  input = 2.048Vdc +  $1V_{pp}$  at 1kHz.



#### TYPICAL CHARACTERISTICS

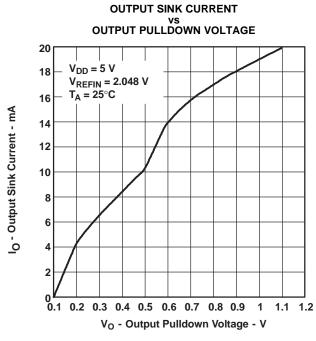


Figure 2.

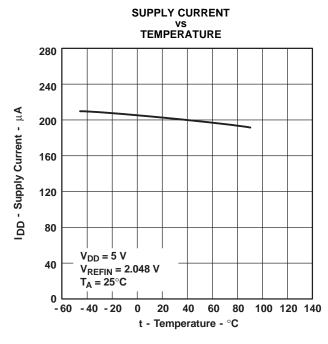


Figure 4.

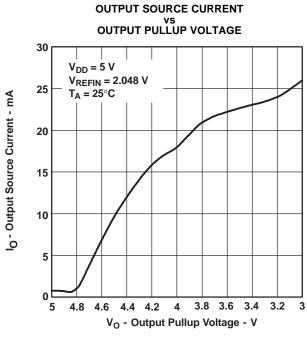


Figure 3.

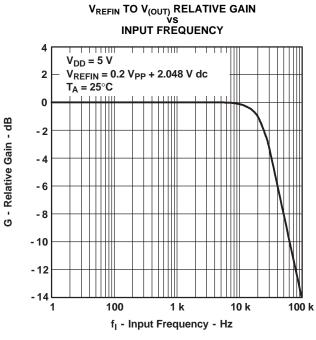


Figure 5.



#### **TYPICAL CHARACTERISTICS (continued)**

# SIGNAL-TO-NOISE + DISTORTION vs INPUT FREQUENCY AT REFIN

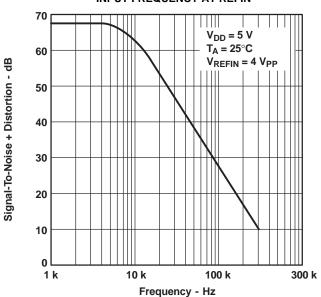


Figure 6.

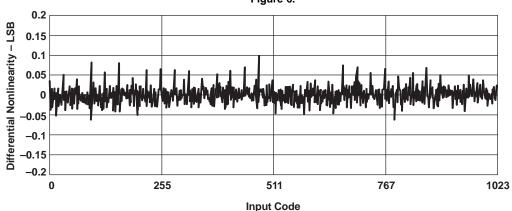


Figure 7. Differential Nonlinearity With Input Code

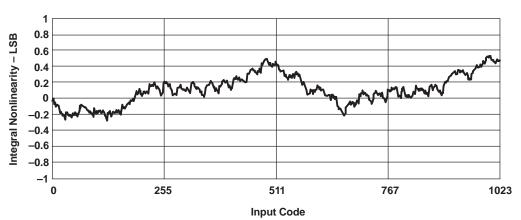


Figure 8. Integral Nonlinearity With Input Code



#### **APPLICATION INFORMATION**

#### **GENERAL FUNCTION**

The TLC5615 uses a resistor string network buffered with an op amp in a fixed gain of 2 to convert 10-bit digital data to analog voltage levels (see functional block diagram and Figure 9). The output of the TLC5615 is the same polarity as the reference input (see Table 1).

An internal circuit resets the DAC register to all zeros on power up.

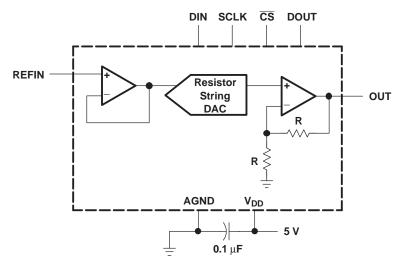


Figure 9. TLC5615 Typical Operating Circuit

Table 1. Binary Code Table (0V to 2V<sub>REFIN</sub>Output), Gain = 2

			, , , , , , , , , , , , , , , , , , , ,
	INPUT <sup>(1)</sup>		OUTPUT
1111	1111	11(00)	$2(V_{REFIN})\frac{1023}{1024}$
	:		:
1000	0000	01(00)	$2(V_{REFIN})\frac{513}{1024}$
1000	0000	00(00)	$2(V_{REFIN})\frac{512}{1024} = V_{REFIN}$
0111	1111	11(00)	$2(V_{REFIN})\frac{511}{1024}$
	:		:
0000	0000	01(00)	$2(V_{REFIN})\frac{1}{1024}$
0000	0000	00(00)	0 V

<sup>(1)</sup> A 10-bit data word with two bits below the LSB bit (sub-LSB) with 0 values must be written since the DAC input latch is 12 bits wide.



#### **BUFFER AMPLIFIER**

The output buffer has a rail-to-rail output with short circuit protection and can drive a  $2k\Omega$  load with a 100pF load capacitance. Settling time is 12.5 $\mu$ s typical to within 0.5LSB of final value.

#### **EXTERNAL REFERENCE**

The reference voltage input is buffered, which makes the DAC input resistance not code dependent. Therefore, the REFIN input resistance is  $10M\Omega$  and the REFIN input capacitance is typically 5pF independent of input code. The reference voltage determines the DAC full-scale output.

#### LOGIC INTERFACE

The logic inputs function with either TTL or CMOS logic levels. However, using rail-to-rail CMOS logic achieves the lowest power dissipation. The power requirement increases by approximately 2 times when using TTL logic levels.

#### SERIAL CLOCK AND UPDATE RATE

Figure 1 shows the TLC5615 timing. The maximum serial clock rate is:

$$f_{(SCLK)max} = \frac{1}{t_{W(CH)} + t_{W(CL)}}$$

or approximately 14MHz. The digital update rate is limited by the chip-select period, which is:

$$t_{p(CS)} = 16 \times \left(t_{w(CH)} + t_{w(CL)}\right) + t_{w(CS)}$$

and is equal to 820ns which is a 1.21 MHz update rate. However, the DAC settling time to 10 bits of  $12.5 \mu s$  limits the update rate to 80 kHz for full-scale input step transitions.

#### **SERIAL INTERFACE**

When chip select  $(\overline{CS})$  is low, the input data is read into a 16-bit shift register with the input data clocked in most significant bit first. The rising edge of the SLCK input shifts the data into the input register.

The rising edge of  $\overline{CS}$  then transfers the data to the DAC register. When  $\overline{CS}$  is high, input data cannot be clocked into the input register. All  $\overline{CS}$  transitions should occur when the SCLK input is low.

If the daisy chain (cascading) function (see daisy-chaining devices section) is not used, a 12-bit input data sequence with the MSB first can be used as shown in Figure 10:

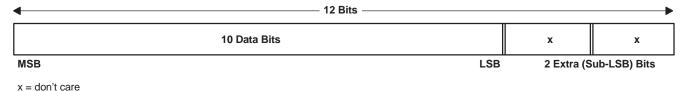


Figure 10. 12-Bit Input Data Sequence

or 16 bits of data can be transferred as shown in Figure 11 with the 4 upper dummy bits first.

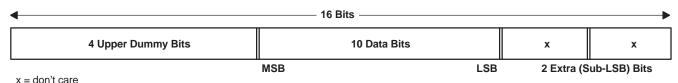


Figure 11. 16-Bit Input Data Sequence

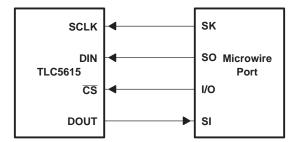


The data from DOUT requires 16 falling edges of the input clock and, therefore, requires an extra clock width. When daisy chaining multiple TLC5615 devices, the data requires 4 upper dummy bits because the data transfer requires 16 input-clock cycles plus one additional input-clock falling edge to clock out the data at the DOUT terminal (see Figure 1).

The two extra (sub-LSB) bits are always required to provide hardware and software compatibility with 12-bit data converter transfers.

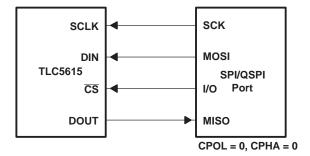
The TLC5615 three-wire interface is compatible with the SPI, QSPI, and Microwire serial standards. The hardware connections are shown in Figure 12 and Figure 13.

The SPI and Microwire interfaces transfer data in 8-bit bytes; therefore, two write cycles are required to input data to the DAC. The QSPI interface, which has a variable input data length from 8 to 16 bits, can load the DAC input register in one write cycle.



NOTE A: The DOUT-SI connection is not required for writing to the TLC5615 but may be used for verifying data transfer if desired.

**Figure 12. Microwire Connection** 



NOTE A: The DOUT-MISO connection is not required for writing to the TLC5615 but may be used for verifying data transfer.

Figure 13. SPI/QSPI Connection

#### **DAISY-CHAINING DEVICES**

DACs can be daisy-chained by connecting the DOUT terminal of one device to the DIN of the next device in the chain, providing that the setup time,  $t_{su(CSS)}$  ( $\overline{CS}$  low to SCLK high), is greater than the sum of the setup time,  $t_{su(DS)}$ , plus the propagation delay time,  $t_{pd(DOUT)}$ , for proper timing (see digital input timing requirements section). The data at DIN appears at DOUT, delayed by 16 clock cycles plus one clock width. DOUT is a totem-poled output for low power. DOUT changes on the SCLK falling edge when  $\overline{CS}$  is low. When  $\overline{CS}$  is high, DOUT remains at the value of the last data bit and does not go into a high-impedance state.

#### LINEARITY, OFFSET, AND GAIN ERROR USING SINGLE-ENDED SUPPLIES

When an amplifier is operated from a single supply, the voltage offset can still be either positive or negative. With a positive offset, the output voltage changes on the first code change. With a negative offset the output voltage may not change with the first code depending on the magnitude of the offset voltage.



The output amplifier attempts to drive the output to a negative voltage. However, because the most negative supply rail is ground, the output cannot drive below ground and clamps the output at 0V.

The output voltage then remains at zero until the input code value produces a sufficient positive output voltage to overcome the negative offset voltage, resulting in the transfer function shown in Figure 14.

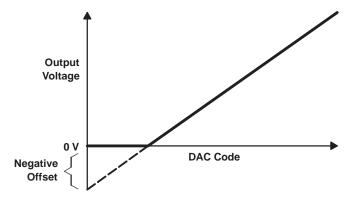


Figure 14. Effect of Negative Offset (Single Supply)

This offset error, not the linearity error, produces this breakpoint. The transfer function would have followed the dotted line if the output buffer could drive below the ground rail.

For a DAC, linearity is measured between zero-input code (all inputs '0') and full-scale code (all inputs '1') after offset and full scale are adjusted out or accounted for in some way. However, single supply operation does not allow for adjustment when the offset is negative due to the breakpoint in the transfer function. So the linearity is measured between full-scale code and the lowest code that produces a positive output voltage. For the TLC5615, the zero-scale (offset) error is ±3LSB maximum. The code is calculated from the maximum specification for the negative offset.

#### POWER-SUPPLY BYPASSING AND GROUND MANAGEMENT

Printed circuit boards that use separate analog and digital ground planes offer the best system performance. Wire-wrap boards do not perform well and should not be used. The two ground planes should be connected together at the low-impedance power-supply source. The best ground connection may be achieved by connecting the DAC AGND terminal to the system analog ground plane making sure that analog ground currents are well managed and there are negligible voltage drops across the ground plane.

A  $0.1\mu F$  ceramic-capacitor bypass should be connected between  $V_{DD}$  and AGND and mounted with short leads as close as possible to the device. Use of ferrite beads may further isolate the system analog supply from the digital power supply.

Figure 15 shows the ground plane layout and bypassing technique.

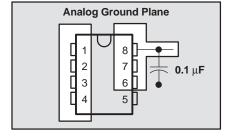


Figure 15. Power-Supply Bypassing

#### **SAVING POWER**

Setting the DAC register to all 0s minimizes power consumption by the reference resistor array and the output load when the system is not using the DAC.



#### **AC CONSIDERATIONS**

#### **Digital Feedthrough**

Even with  $\overline{\text{CS}}$  high, high-speed serial data at any of the digital input or output terminals may couple through the DAC package internal stray capacitance and appear at the DAC analog output as digital feedthrough. Digital feedthrough is tested by holding  $\overline{\text{CS}}$  high and transmitting 0101010101 from DIN to DOUT.

#### **Analog Feedthrough**

Higher frequency analog input signals may couple to the output through internal stray capacitance. Analog feedthrough is tested by holding  $\overline{\text{CS}}$  high, setting the DAC code to all 0s, sweeping the frequency applied to REFIN, and monitoring the DAC output.





## **Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

CI	Changes from D Revision (August 2003) to E Revision						
•	Added ESD statement.	2					
•	Changed —moved package option table from front page.	2					







#### **PACKAGING INFORMATION**

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	e Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp (3)
TLC5615CD	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615CDG4	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615CDGK	ACTIVE	MSOP	DGK	8	80	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615CDGKG4	ACTIVE	MSOP	DGK	8	80	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615CDGKR	ACTIVE	MSOP	DGK	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615CDGKRG4	ACTIVE	MSOP	DGK	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615CDR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615CDRG4	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615CP	ACTIVE	PDIP	Р	8	50	Pb-Free (RoHS)	CU NIPDAU	N / A for Pkg Type
TLC5615CPE4	ACTIVE	PDIP	Р	8	50	Pb-Free (RoHS)	CU NIPDAU	N / A for Pkg Type
TLC5615ID	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615IDG4	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615IDGK	ACTIVE	MSOP	DGK	8	80	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615IDGKG4	ACTIVE	MSOP	DGK	8	80	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615IDR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615IDRG4	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TLC5615IP	ACTIVE	PDIP	Р	8	50	Pb-Free (RoHS)	CU NIPDAU	N / A for Pkg Type
TLC5615IPE4	ACTIVE	PDIP	Р	8	50	Pb-Free (RoHS)	CU NIPDAU	N / A for Pkg Type

 $<sup>^{(1)}</sup>$  The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

TBD: The Pb-Free/Green conversion plan has not been defined.

**Pb-Free** (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.



#### PACKAGE OPTION ADDENDUM

28-Aug-2008

package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

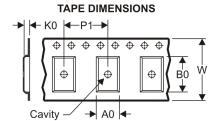
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#### TAPE AND REEL INFORMATION





	Dimension designed to accommodate the component width
	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device		Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TLC5615CDGKR	MSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
TLC5615CDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
TLC5615CDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
TLC5615IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
TLC5615IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1



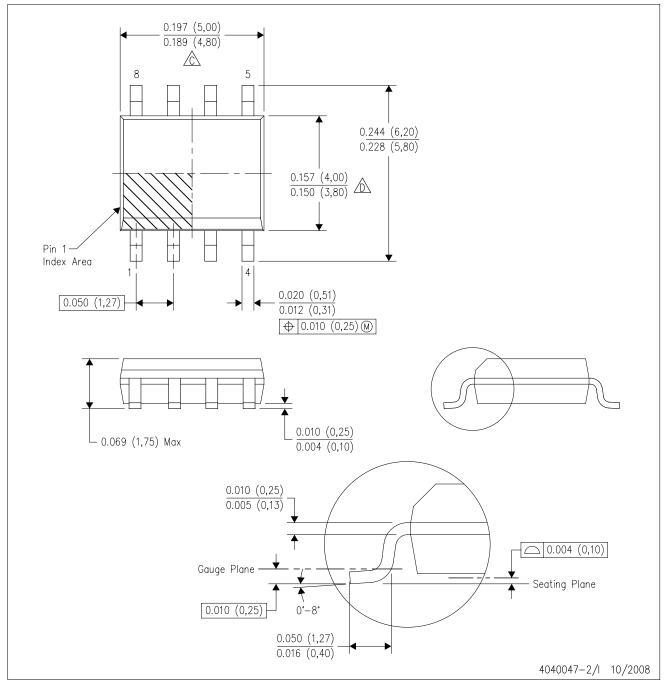


\*All dimensions are nominal

All differences are normal							
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TLC5615CDGKR	MSOP	DGK	8	2500	346.0	346.0	29.0
TLC5615CDR	SOIC	D	8	2500	346.0	346.0	29.0
TLC5615CDR	SOIC	D	8	2500	340.5	338.1	20.6
TLC5615IDR	SOIC	D	8	2500	340.5	338.1	20.6
TLC5615IDR	SOIC	D	8	2500	346.0	346.0	29.0

## D (R-PDSO-G8)

#### PLASTIC SMALL-OUTLINE PACKAGE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 (0,15) per end.
- Body width does not include interlead flash. Interlead flash shall not exceed .017 (0,43) per side.
- E. Reference JEDEC MS-012 variation AA.



## DGK (S-PDSO-G8)

## PLASTIC SMALL-OUTLINE PACKAGE



NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 per end.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.50 per side.
- E. Falls within JEDEC MO-187 variation AA, except interlead flash.



#### P (R-PDIP-T8)

#### PLASTIC DUAL-IN-LINE



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MS-001

For the latest package information, go to http://www.ti.com/sc/docs/package/pkg\_info.htm

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